NGGPS Workshop 02/10/2016 College Park, MD

Global Model Test Bed (GMTB)

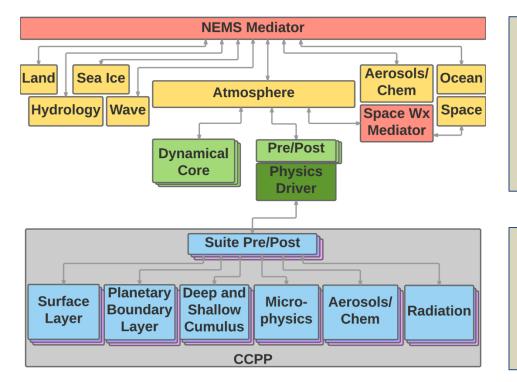
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Developmental Testbed Center

Acknowledgements

GMTB team
EMC staff
NGGPS collaborators
NUOPC PI team



Motivation for GMTB



NGGPS

New NCEP global model will use community codes — a strategy to enhance rate of transition of research to operations

GMTB

Is a critical mechanism for connecting NCEP to the research community

Leverage from the Developmental Testbed Center

GMTB builds on the DTC multi-year of supporting R2O for regional NCEP NWP codes, such as Hurricane WRF and GSI data assimilation

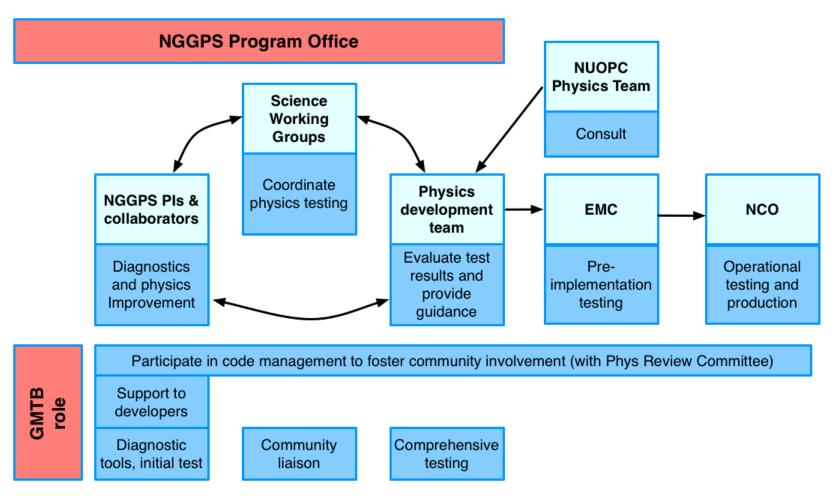


Atmospheric Physics

Supporting development of parameterizations



GMTB's role in physics development





NGGPS code management protocols

https://docs.google.com/document/d/1bjnyJpJ7T3XeW3zCnhRLTL5a3m4_3XIAUeThUPWD9Tg/edit#heading=h.ku78qulk21xh

Code, Data, and Document Management for NEMS Modeling Applications and Suites - DRAFT

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Purpose
Overall Goals

NGGPS OAS

GMTB is collaborating with OAS to create code management protocols for NEMS-based suites

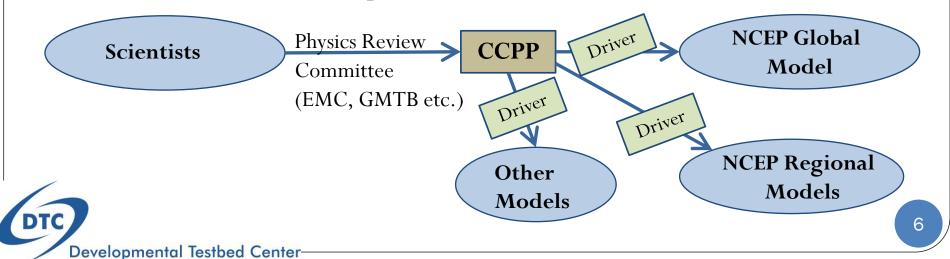
NOAA Virtual Laboratory

- GMTB started a project on Vlab for development of the Single Column Model
- Gives GMTB experience with Vlab and Git repositories, which will be useful to investigate possible transition of significant part of NGGPS code base to VLab

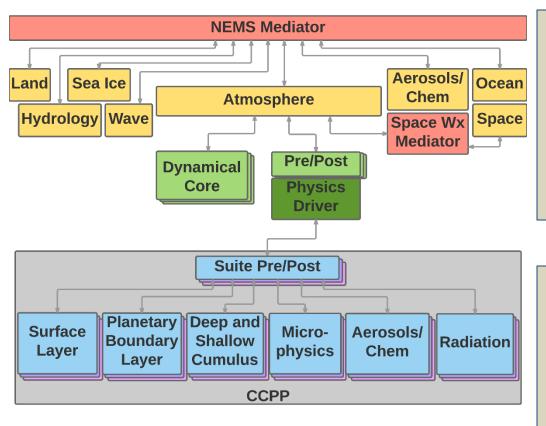


Proposed vision for Driver & CCPP

- CCPP is a <u>library of dycore-agnostic atmospheric physical</u> <u>parameterizations</u> to be used by NCEP models
 - Start with global, but could be used by regional models as well
 - CCPP could be used with any dycore that connects to the <u>Driver</u>
- Various parameterizations of each category can co-exist in the CCPP, but a <u>Physics Review Committee</u> constrains options based on objective and transparent criteria



Schematic for Driver & CCPP



Pre/Post Physics interfaces have knowledge of dycore

If necessary, they de- and re-stagger, and convert between dycore variables and Driver standard variables.

Pre/Post Parameterization interface has knowledge of the parameterizations

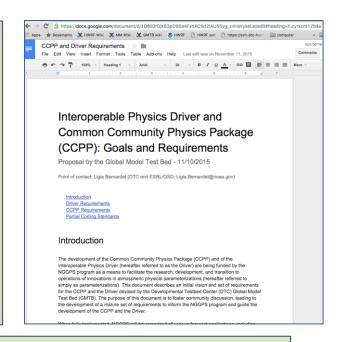
If necessary, they re-order and convert variables between the Driver and the parameterizations

Collaboration with NUOPC PITeam and EMC

CCPP and Driver

CCPP benefits to NOAA

- Community participation in physics development
 & testing will expedite improvement of NGGPS
 forecasts
- Hierarchical testing framework including SCM will attract community contributions
- A single library of physics that can be used by all models will minimize need to port new schemes to various NCEP models



Current status

- Initial CCPP capability will be based on operational GFS physics documentation and testbed preparations are underway
- Goals and requirements for CCPP & Driver proposed and presented by GMTB
 - Requires Driver that can work with parameterizations other than GFS'
 - EMC will further develop the driver, all need to agree on requirements
 - Code management discussions have started but need to progress



Documentation for physical parameterizations in CCPP

- Introduction
 - Scientific origin (including references) and history
 - What the scheme calculates and key features
- Summary of how the scheme works
- Diagram depicting calling hierarchy
- Source files and associated subroutines and functions
- Intra-physics communication
 - Variables exchanged between routines
- For each subroutine, further documentation
 - Description, what is done in the subroutine
 - Argument list: variable names, "intent", shape size, short description, units
 - Overview of the steps of the algorithm
 - If available, algorithm description with equations, discretization, etc.

GMTB has started preparing documentation for CCPP (starting with operational GFS physics)

CCPP Doxygen-based Documentation

GFS Operational Physics Documentation

▼ GFS Operational Phy

▼ GFS Operational

Structure Todo List

Bibliography

- Modules
- ▶ Files

GFS Operational Physics

Documentation for the operational physics suite car

- · Radiation RRTMG
- Turbulent Transport (PBL) Hybrid EDMF
- Penetrative Convection SAS
- Shallow Convection SAS
- Cloud Microphysics Zhao-Carr
- · Gravity Wave Drag Orographic GWD, Static
- · Ozone Physics NRL simplified scheme
- Land Surface Model NOAH

Hybrid Eddy-diffusivity Mass Flux Scheme

The Hybrid EDMF scheme is a first-order turbulent transport scheme used for subgrid-scale vertical advection in the F used and improved over the last several years with a more recent scheme that uses a mass-flux approach to calculate

Detailed Description

The PBL scheme's main task is to calculate tendencies of temperature, moisture, and momentum due to vertical diffus amalgamation of decades of work, starting from the initial first-order PBL scheme of Troen and Mahrt (1986) [11], imp down mixing due to stratocumulus layers from Lock et al. (2000) [6] and replacement of counter-gradient terms with a (2004) [10]. Recently, heating due to TKE dissipation was also added according to Han et al. (2015) [3].

Calling Hierarchy Diagram

Detailed Algorithm

Since the mfpbl subroutine is called regardless of whether the PBL is convective, a check of the convective PBL flag is performed output variables set to the initialized values) if the PBL is not convective.

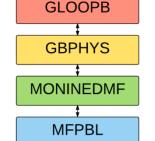
Determine an updraft parcel's entrainment rate, buoyancy, and vertical velocity.

Calculate the entrainment rate according to equation 16 in Siebesma et al. (2007) [9] for all levels (xlamue) and a default entrainment

Using equations 17 and 7 from Siebesma et al (2007) [9] along with u_* , w_* , and the previously diagnosed PBL height, the initial θ

From the second level to the middle of the vertical domain, the updraft virtual potential temperature is calculated using to (2007) [9], discretized as

$$\frac{\theta_{v,u}^k - \theta_{v,u}^{k-1}}{\Delta_{v,u}} = -\epsilon^{k-1} \left[\frac{1}{2} \left(\theta_{v,u}^k + \theta_{v,u}^{k-1} \right) - \frac{1}{2} \left(\overline{\theta_v}^k + \overline{\theta_v}^k \right) \right]$$



Parameters

[in]

is

horizontal dimension

[in]

km

number of used points vertical layer dimension



Developmental Testbed Center



Driver Documentation

Physics Driver Users' Guide Vx.x

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NOAA/ESRL Global Systems Division, Developmental Testbed Center and CIRES/CU

James Rosinski

NOAA/ESRL Global Systems Division, Developmental Testbed Center and CIRA/CSU

Acknowledgements



Outline of Documentation

- 1. Overview
- 2. Using the Standalone Driver
- 3. Memory Management
- 4. Initialization Process
- 5. Run Process
- 6. Finalize Process
- 7. Connecting the IPD with a Dycore
- 8. Limitations of the prototype
- 9. Code Management
- 10.Help and support

GMTB has started preparing documentation for Driver (building on initial EMC effort)



Testbed



Hierarchical testing

GMTB/EMC Testing Hierarchy

Parameterization Simulator

Individual PPs

Single Column Model

Many Interacting PPs

Limited Area Domain

Detailed Phenomenological

LR Global Offline (Reforecast)

Mechanical

LR/MR Global Forecast Mode

Global PP Interactions; First Verification

HR Global Forecast Mode

LR/MR Global DA Mode

Global Tuning Test

LR Global Climate Mode

LR Global Coupled Mode

EMC Pre-Implementation

NCO Pre-Implementation

> EMC "Level 2"
Preliminary Testing

Responsibility Legend

Physics Dev.

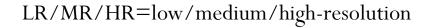
DTC

NOAA EMC

GMTB will provide a testbed to the research community for conducting initial testing of physical parameterizations

- Case studies, datasets
- Scrips/Workflow
- Vx, diagnostics
- Documentation and support

Physical parameterizations that pass initial tests can be transferred to EMC for further testing

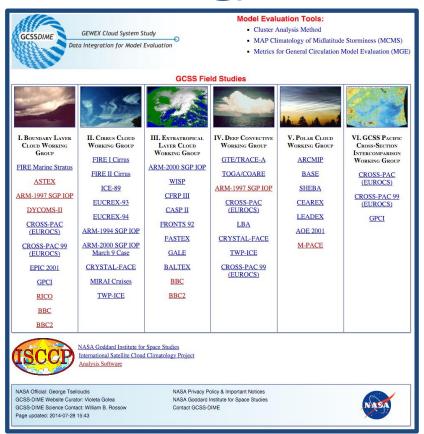


Status of Single Column Model (SCM)

- Completed initial design and started a prototype
 - Relies on Driver and CCPP (initially operational GFS physics)
 - Supports multiple vertical grids and numerical methods adaptable to GFS and new dycore
 - Prototype uses Python layer to call Driver and CCPP
 - Python takes care of I/O, initialization, time-integration, applying forcing
 - Python allows quick prototype and has many data analysis & plotting modules
 - Utility f2py makes Fortran called from Python
- Selected case studies and started preparing datasets



Strategy for using SCM



http://gcss-dime.giss.nasa.gov/

Cases

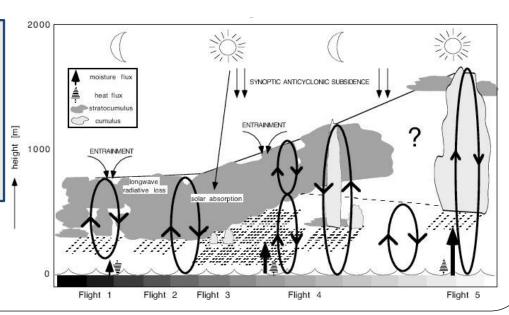
- Collection of cases spanning large range of meteorological conditions
- Geographically well-distributed
- Draws heavily from GEWEX
 - Well-defined cases based on field campaign
 - Published SCM and LES intercomparisons
 - Data and intercomparisons available
- **GMTB will:** produce baseline for each case using GFS operational physics suite
- Researchers will: be able to quickly run SCM cases and compare their results using novel parameterizations against baseline



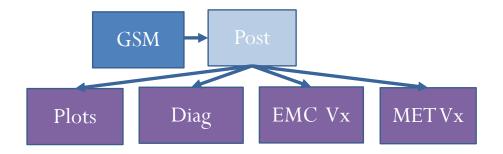
GMTB SCM Initial Case

- ASTEX Lagrangian (Atlantic Stratocumulus to cumulus Transition Experiment)
- Features a precipitating Sc-to-Cu transition (40-h integration from obs)
- Forcings mimic a column being advected from northern Hadley Cell region (stratocumulus) to middle Hadley Cell region (trade-wind cumulus)
- Presents a challenge for SCMs (the transition between regimes is delicate; the timing and details of the PBL decoupling provide important clues about a physics suite's global performance)

This case tests interaction among following scheme types: surface layer, PBL, shallow convection, radiation, and microphysics (deep convection is on, but largely inactive)



Testbed for global model on Theia



Close collaboration DTC/EMC in setting up scripts/testbed

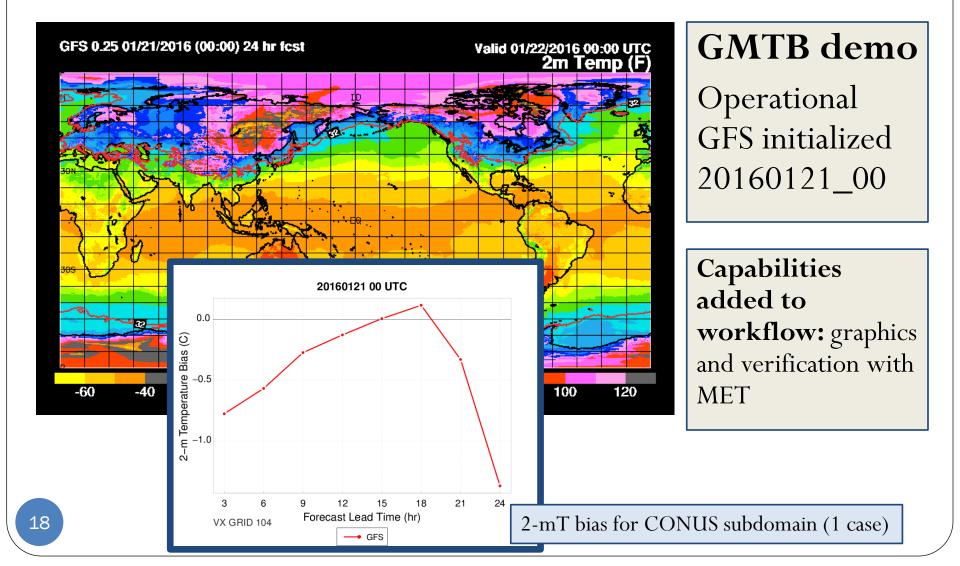
- Successful ramp up in GMTB staff expertise with GSM
- Issues related to postprocessing being worked out together by EMC/DTC
- Scripts draw libraries, executables and input files from various locations on theia: work ahead in creating a controlled, understandable environment for community

Connection with NGGPS Vx Team

Looking toward unification of NOAA Vx (MET, EMC, GSD/EMB/HIWPP)



Example: GFS 2-m T + MET Vx



A friendlier IT environment for R20



NWP Information Technology Environment (NITE)

In 2015 DTC prepared a report on elements that would make it more straight forward for community scientists to interact with NCEP modeling suites

- EMC starting to implement aspects of NITE for NGGPS
- GMTB is providing input and will benefit from upgraded environment



Selection of a sea-ice model



Sea Ice Modeling Workshops

- Committee
 - J. Intrieri (NOAA, ESRL), M. Holland (NCAR), B. Grumbine (NOAA EMC), C. Bitz (U. Washington), R. Allard (NRL), and A. Mariotti (NOAA OAR/CPO), Eugene Petrescu (NOAA NWSAK)
 - Participants: EMC, GMTB, ESRL, NRL, NWS AK, LANL, GFDL, GLERL, UW, E Canada, NPS, ONR, Natl Snow Ice Data Center
- **Date and location**: 2-4 February 2016 at NCAR, Boulder
- Context: Back-to-back ONR SeaState and NGGPS sea-ice workshops
- Goals: Review state-of-art and lessons from ONR SeaState initiative, candidate models for NGGPS, selection criteria, predictability, performance, skill metrics, testing considerations, R&D needs & opportunities for coordination, recommendations on the selection process

Recommendations to NGGPS

• Recommend possible adoption of CICE due to its extensive use in the community and excellent documentation and resources

Justification

- Most sea ice models have state-of-the-art physics
- Instead of investing on intercomparison, test/improve/develop one model

Consortium

- Intellectual property issues need to be addressed to make CICE a true community model
- Governance must support NGGPS needs





GMTB Summary

- Opportunities: NGGPS offers opportunity to bring the physics community together in a novel way: broad spectrum of expertise focused on a common problem. Given the right framework, group can make fast progress toward improving the NCEP global model
- **Challenge:** Developing a CCPP/Driver package that will effectively facilitate physics advancement and conducting T&E that is relevant to all involved will require close cross-institution coordination (DTC, EMC, physics developers)

Stay tuned for upcoming NGGPS Physics Principal Investigators Workshop Sep 2016